

NPTEL Video Lecture Topic List - Created by LinuXpert Systems, Chennai

NPTEL Video Course - Physics - NOC:Control System Design

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Co-ordinating Institute - IISc - Bangalore

Sub-Titles - Available / Unavailable | MP3 Audio Lectures - Available / Unavailable

Lecture 1 - Introduction

Lecture 2 - Linear Systems

Lecture 3 - Homogeneous linear time invariant ordinary differential equations

Lecture 4 - In-homogeneous linear time invariant ordinary differential equations

Lecture 5 - Fourier transforms - Part 1

Lecture 6 - Fourier transforms - Part 2

Lecture 7 - Laplace transforms - Part 1

Lecture 8 - Laplace transforms - Part 2

Lecture 9 - Introduction to feedback control - Part 1

Lecture 10 - Introduction to feedback control - Part 2

Lecture 11 - Nyquist stability theory - Part 1

Lecture 12 - Nyquist stability theory - Part 2

Lecture 13 - Nyquist stability theory - Part 3

Lecture 14 - Bode plots

Lecture 15 - Steps for performing control design - Part 1

Lecture 16 - Steps for performing control design - Part 2

Lecture 17 - General controllers - Part 1

Lecture 18 - General controllers - Part 2

Lecture 19 - General controllers - Part 3

Lecture 20 - Bode plot-based control design - Part 1

Lecture 21 - Bode plot-based control design - Part 2

Lecture 22 - Introduction to root-locus

Lecture 23 - Control system design using root-locus

Lecture 24 - Control of systems with some known parameters - Part 1

Lecture 25 - Control of systems with some known parameters - Part 2

Lecture 26 - Limitations of 1-degree of freedom control

Lecture 27 - Introduction to 2-degree of freedom control

Lecture 28 - 2-Degree of freedom robust control design for plants with gain uncertainty - Part 1

Lecture 29 - 2-Degree of freedom robust control design for plants with uncertain gain - Part 2

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- Lecture 30 - 2-Degree of freedom robust control design for plants with uncertain pole
- Lecture 31 - 2-Degree of freedom robust control design for plants with multiple uncertainties in their structure
- Lecture 32 - Issues connected with 2-Degree of freedom control design using root-locus
- Lecture 33 - Introduction to Nichols plot
- Lecture 34 - Feedback control design using Nichols plot
- Lecture 35 - Robust control design using Quantitative feedback theory - Part 1
- Lecture 36 - Robust control design using Quantitative feedback theory - Part 2
- Lecture 37 - Tutorial on QFT Toolbox software - Part 1
- Lecture 38 - Tutorial on QFT Toolbox software - Part 2
- Lecture 39 - Tutorial on QFT Toolbox software - Part 3
- Lecture 40 - Fundamental properties of the loop gain - Part 1
- Lecture 41 - Fundamental properties of the loop gain - Part 2
- Lecture 42 - Ideal Bode Characteristic - Part 1
- Lecture 43 - Ideal Bode Characteristic - Part 2
- Lecture 44 - Introduction to nonminimum phase systems
- Lecture 45 - Fundamental properties of nonminimum phase systems - Part 1
- Lecture 46 - Fundamental properties of nonminimum phase systems - Part 2
- Lecture 47 - Fundamental properties of unstable systems
- Lecture 48 - Consequences of actuator bandwidth limitations while controlling unstable systems
- Lecture 49 - Describing functions - Part 1
- Lecture 50 - Describing functions - Part 2