

NPTEL Video Lecture Topic List - Created by LinuXpert Systems, Chennai

NPTEL Video Course - Electrical Engineering - NOC:Control Engineering

Subject Co-ordinator - Prof. Ramkrishna.P

Co-ordinating Institute - IIT - Madras

Sub-Titles - Available / Unavailable | MP3 Audio Lectures - Available / Unavailable

Lecture 1 - Introduction to Systems and Control

Lecture 2 - Modelling of Systems

Lecture 3 - Elements of Modelling

Lecture 4 - Examples of Modelling

Lecture 5 - Solving Problems in Modelling of Systems

Lecture 6 - Laplace Transforms

Lecture 7 - Inverse Laplace Transforms

Lecture 8 - Transfer Function of Modelling Block Diagram Representation

Lecture 9 - Solving Problems on Laplace Transforms and Transfer Functions

Lecture 10 - Block Diagram Reduction, Signal Flow Graphs

Lecture 11 - Solving Problems on Block Diagram Reduction, Signal Flow Graphs

Lecture 12 - Time Response Analyzsis of systems

Lecture 13 - Time Response specifications

Lecture 14 - Solving Problems on Time Response Analyzsis ans specifications

Lecture 15 - Stability

Lecture 16 - Routh Hurwitz Criterion

Lecture 17 - Routh Hurwitz Criterion T 1

Lecture 18 - Closed loop System and Stability

Lecture 19 - Root Locus Technique

Lecture 20 - Root Locus Plots

Lecture 21 - Root Locus Plots (Continued...)

Lecture 22 - Root Locus Plots (Continued...)

Lecture 23 - Root Locus Plots (Continued...)

Lecture 24 - Introduction to Frequency Response

Lecture 25 - Frequency Response Plots

Lecture 26 - Relative Stability

Lecture 27 - Bode plots

Lecture 28 - Basics of Control design Proportional, Integral and Derivative Actions

Lecture 29 - Basics of Control design Proportional, Integral and Derivative Actions

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- Lecture 30 - Problems on PID Controllers
- Lecture 31 - Basics of Control design Proportional, Integral and Derivative Actions
- Lecture 32 - Control design in time domain and discusses the lead compensator
- Lecture 33 - Improvement of the Transient Response using lead compensation
- Lecture 34 - Design of control using lag compensators
- Lecture 35 - The design of Lead-Lag compensators using root locus
- Lecture 36 - Introduction design of control in frequency domain
- Lecture 37 - Design of Lead Compensator using Bode Plots
- Lecture 38 - Design of Lag Compensators using Bode Plots
- Lecture 39 - Design of Lead-Lag Compensators using Bode plots
- Lecture 40 - Experimental Determination of Transfer Function
- Lecture 41 - Effect of Zeros on System Response
- Lecture 42 - Navigation - Stories and Some Basics
- Lecture 43 - Navigation - Dead Reckoning and Reference Frames
- Lecture 44 - Inertial Sensors and Their Characteristics
- Lecture 45 - Filter Design to Attenuate Inertial Sensor Noise
- Lecture 46 - Complementary Filter
- Lecture 47 - Complementary Filter - 1
- Lecture 48 - Introduction to State Space Systems
- Lecture 49 - Linearization of State Space Dynamics
- Lecture 50 - Linearization of State Space Dynamics - 1
- Lecture 51 - Controllability and Observability