## NPTEL Video Lecture Topic List - Created by LinuXpert Systems, Chennai

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NPTEL Video Course - Aerospace Engineering - Advanced Control System Design for Aerospace Vehicles
Subject Co-ordinator - Dr. Radhakant Padhi
Co-ordinating Institute - IISc - Bangalore
Sub-Titles - Available / Unavailable | MP3 Audio Lectures - Available / Unavailable
Lecture 1 - Introduction and Motivation for Advanced Control Design
Lecture 2 - Classical Control Overview - I
Lecture 3 - Classical Control Overview - II
Lecture 4 - Classical Control Overview - III
Lecture 5 - Classical Control Overview - IV
Lecture 6 - Basic Principles of Atmospheric Flight Mechanics
Lecture 7 - Overview of Flight Dynamics - I
Lecture 8 - Overview of Flight Dynamics - II
Lecture 9 - Representation of Dynamical Systems - I
Lecture 10 - Representation of Dynamical Systems - II
Lecture 11 - Representation of Dynamical Systems - III
Lecture 12 - Review of Matrix Theory - I
Lecture 13 - Review of Matrix Theory - II
Lecture 14 - Review of Matrix Theory - III
Lecture 15 - Review of Numerical Methods
Lecture 16 - Linearization of Nonlinear Systems
Lecture 17 - First and Second Order Linear Differential Equations
Lecture 18 - Time Response of Linear Dynamical Systems
Lecture 19 - Stability of Linear Time Invariant Systems
Lecture 20 - Controllability and Observability of linear Time Invariant Systems
Lecture 21 - Pole Placement Control Design
Lecture 22 - Pole Placement Observer Design
Lecture 23 - Static Optimization
Lecture 24 - Calculus of Variations
Lecture 25 - Optimal Control Formulation using Calculus of Variations
Lecture 26 - Classical Numerical Methods for Optimal Control
Lecture 27 - Linear Quadratic Regulator (LQR) Design - 1
Lecture 28 - Linear Quadratic Regulator (LQR) Design - 2
Lecture 29 - Linear Control Design Techniques in Aircraft Control - I
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## NPTEL Video Lecture Topic List - Created by LinuXpert Systems, Chennai

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Lecture 30 - Linear Control Design Techniques in Aircraft Control - II
Lecture 31 - Lyapunov Theory - I
Lecture 32 - Lyapunov Theory - II
Lecture 33 - Constructions of Lyapunov Functions
Lecture 34 - Dynamic Inversion - I
Lecture 35 - Dynamic Inversion - II
Lecture 36 - Neuro-Adaptive Design - I
Lecture 37 - Neuro-Adaptive Design - II
Lecture 38 - Neuro-Adaptive Design for Flight Control
Lecture 39 - Integrator Back-Stepping; Linear Quadratic (1Q) Observer
Lecture 40 - An Overview of Kalman Filter Theory
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